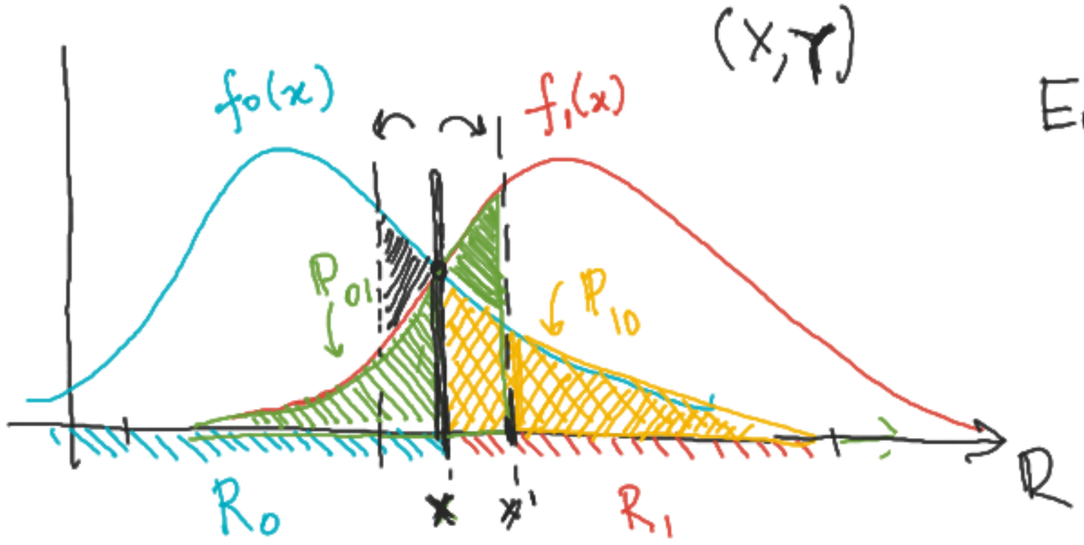
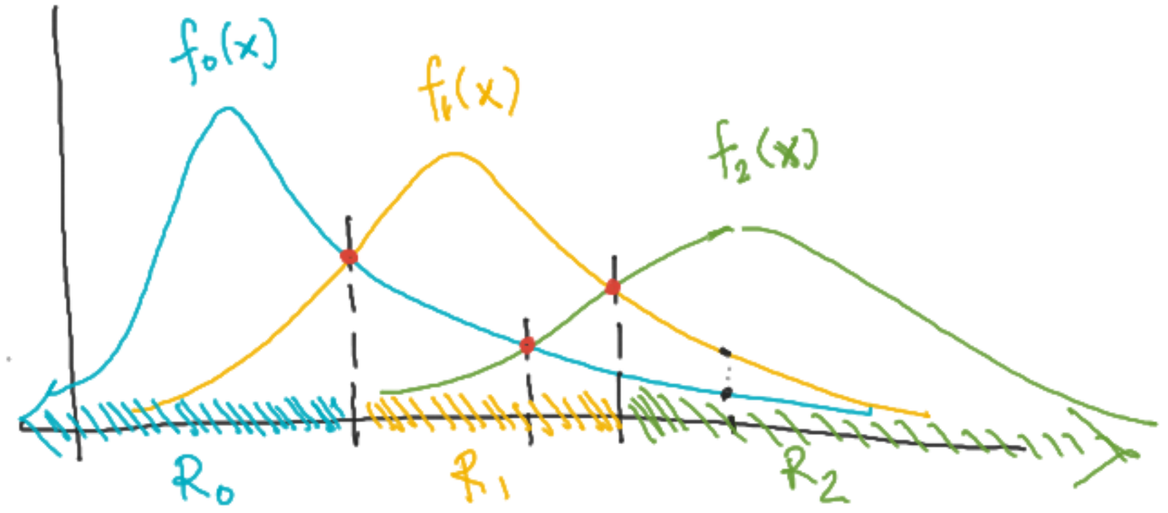
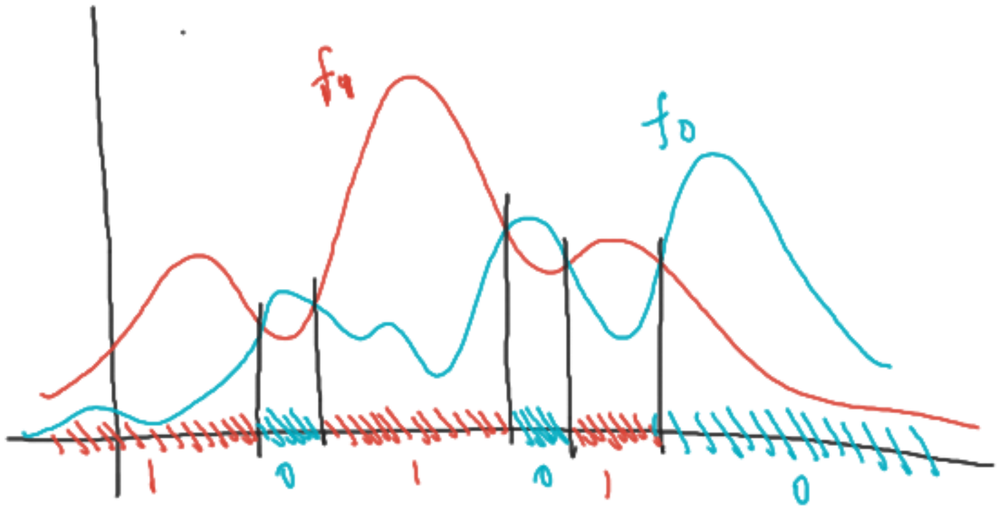
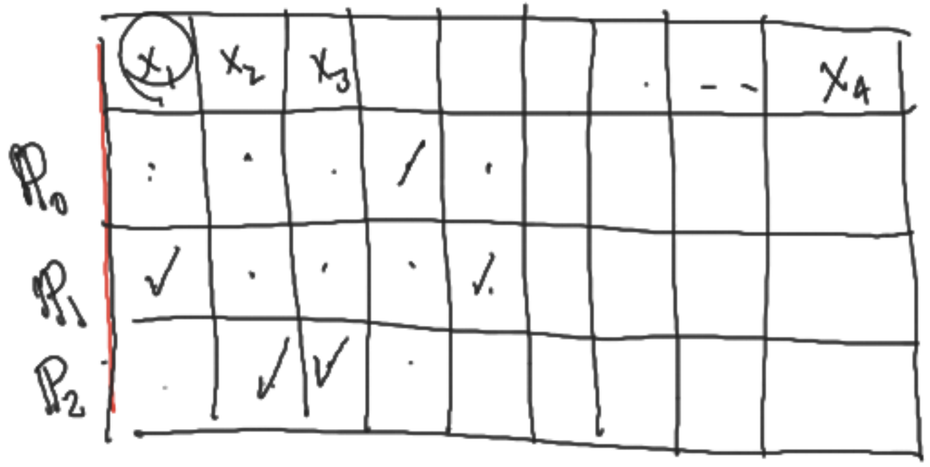


$$\text{Error} = \mathbb{P}(\hat{y}=1 \mid y=0) + \mathbb{P}(\hat{y}=0 \mid y=1)$$

$\mathbb{P}_{10}$ $\quad$ P_{01}




f_1
f_0
1
0
1
0
1
0


x_1
x_2
x_3
x_4
P_0
P_1
P_2

(x_i, y_i) $\quad x_i = (x_{i1}, x_{i2}, x_{i3}, \dots, x_{id}) \in \mathbb{R}^d$

$$X = \begin{bmatrix} x_1 & x_2 & \cdots & x_d \\ | & | & | & | \\ | & | & | & | \\ | & | & | & |

$$\begin{cases} y=0: & P(y=0 \mid X=x) = 9/125 \longrightarrow 9/12 = 3/4 \\ y=1 & P(y=1 \mid X=x) = 3/125 \longrightarrow 3/12 = 1/4 \end{cases}$$

$12/125$

$X = (\text{rojo}, \text{SUV}, \text{dom})$ $\qquad P(y=1 \mid X=x) = 1/4.$